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SECTION 3

DIGITIZATION OF INDUSTRY

004.896:621.865

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MANIPULATOR ROBOT CONTROL SYSTEM USING EYE MOTION

The design of the developed model of the rehabilitation system for paralyzed disabled people based on a robotic arm and software for controlling the data by the robot using an eye tracker is described.

Keywords: robot, manipulator, control, eye-tracker.

My Spoon () [1]

[2],

[3].

() [4].

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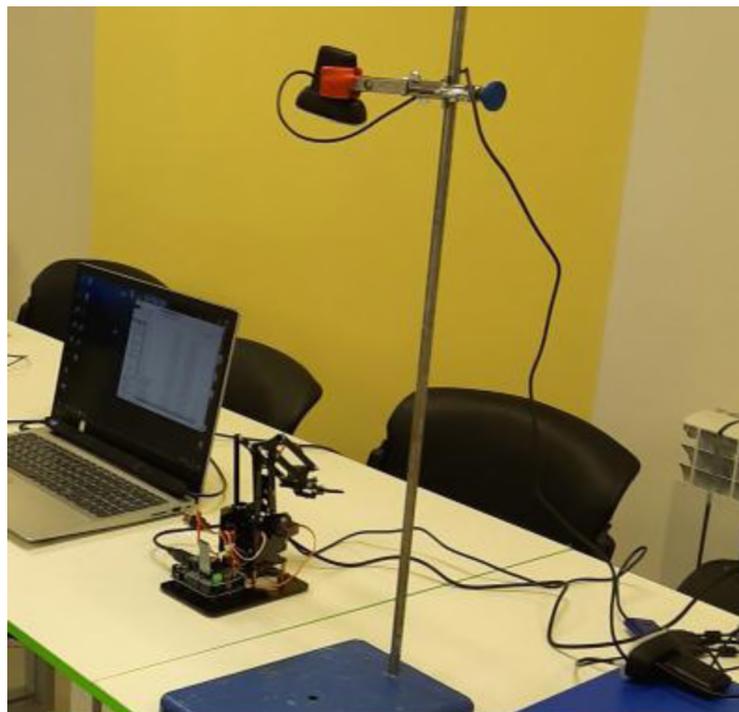
Tracker 4C (. 1).

Arduino.

. 2.



1 - Tobii Eye Tracker 4C



2 -

. 3.

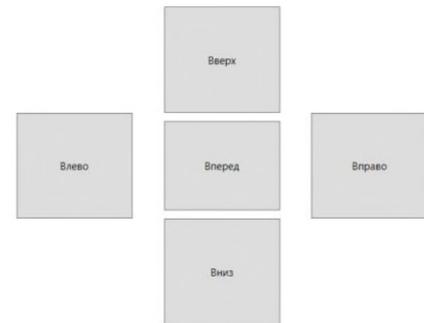
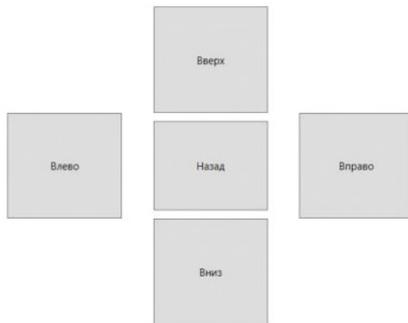
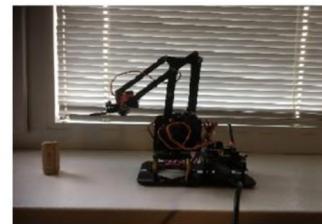
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MainWindow
Калибровка Настройки Помощь



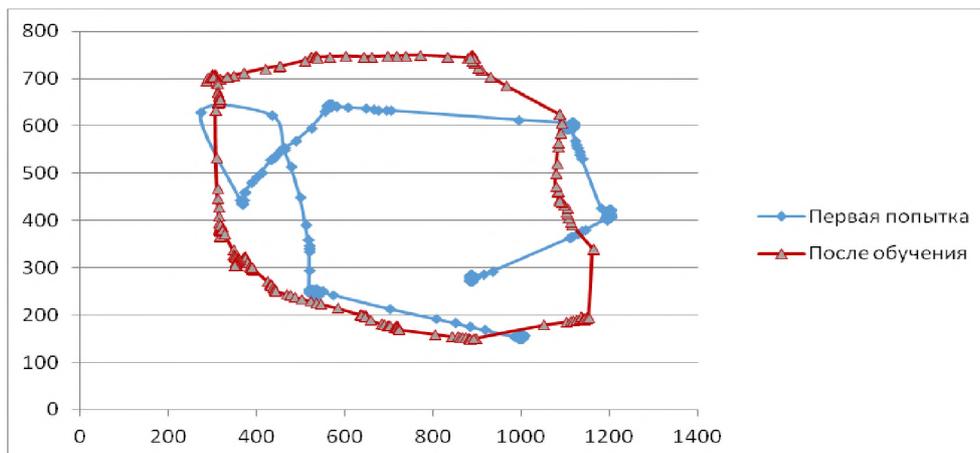
Отпустить

Захват



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20-08-01178.

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2.

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