

001.51; 005

S.I. MATORIN, V.V. MIKHELEV, A.G. ZHIKHAREV

SYSTEM-OBJECTIVE REPRESENTATION OF CONCEPTUAL KNOWLEDGE WITH DESCRIPTION LOGIC

The paper uses the possibilities of applying the system-object approach « Unit-Function-Object» in terms of descriptive logic for describing conceptual knowledge. Conceptual knowledge is represented using a hierarchy of conceptual systems. The results allow us to improve the existing ways of presenting conceptual knowledge, as well as develop models of conceptual knowledge that reflect the systemic reality that exists when solving classification problems.

Keywords: system-object approach «Unit-Function-Object», the presentation of conceptual knowledge, conceptual systems, systems-classes, systems-facts, descriptive logic.

[1].

3].

[7, 8]

... () .

... () [9-11].

... ()

... ()

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() .

1. « - - »

... (. .) ,

[12].

... ,

... ,

... ,

(- -) ,

... , [7, 8].

fs(Ls?)Ls!; (Os?, Os!, Osf), (Ls?, Ls!) - Ls?

fs(Ls?)Ls! - fs, Ls!

; (Os?, Os!, Osf) - ()

(, ,) .

^ , -

[8]:

$$VS' 3AS' = [S^{i-1}; RS'cRS^{i-1}], \quad (1)$$

$S'^i - US \quad S;$

$S^i; \wedge -$
2.

$R^{\wedge} (FS^i S^i RS^i$

$ALC [13, 14]$

ALC

$\{ ; 1; ; / ^ / / U D; . ; VR. \}$

$C, D -$

$R -$

$A -$

$- ABox.$

$K = TBox \wedge ABox.$

$[14].$

$ALCOIQ$

ALC

$ALCOIQ,$

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$ALC [13].$

$ALCOIQ$

$RBox ($

$TBox ABox),$

$SHOIQ$

R

$S, S -$

$R \wedge S, R, S -$

$R.$

3.

$($

$)$

$SHOIQ$

$\ll \gg \ll \gg$

$(t) - (),$

$() -$

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$C^{nt}(S_j) = i \ 3RS^i \wedge,$

$i = 0, N, i -$

$; l, j, I_j, p_j -$

$(-).$

$(V D) -$

$;$

$;$

$Vol(s^j) = s^j \wedge, i \ s_{i,2} \ s_i \wedge N,$

$s^j \wedge \ s_{jj}, p = 1, Ni. Nj -$

$i-$

... , « » [15].
 , - ().

$\frac{1}{(-)}$
 (-) ,
 .
 i - , j - , l -
 SHOIQ,
 « » (Vol) « » (Cont) - : S^{ij} - , RS^{ij} -
 ().

, - () s_{Ji} , S^{ij} , . . .
 S<sub>t,+ \ S_{jj} . - (-) RS^{j^} ^ .
 RS_j, RS^{j^i} RSh</sub>

RBox :

$$TBox = \left| \begin{matrix} SI_{1,P} & S_j \\ \end{matrix} \right| ; RBox = \left| \begin{matrix} RSU_p & RS_j \\ \end{matrix} \right| \quad (2)$$

(1) , - ()
 S^{jj}.

, RS_{ji} - RS_j . RS_j . RS_j -
 , . . . (-) .
 - S_j SHOIQ.
 :

s_{lj} , 3^{rsj} ; ^ .
 I_j - (-) s_j ; P_j
 - - S_{ij} .

(1).
 TBox RBox :

$$TBox = \left| \begin{matrix} S_j & SI_{1,P} & SRS^{ip^} \\ \end{matrix} \right| ; RBox = \left| \begin{matrix} RS_{jj} & RS_{n_{ij}} & 3RS_{kipjj} \\ \end{matrix} \right|$$

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SHOIQ

ALCOIQ

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(18-07-00355 , 18-07-00356 , 19-07-00290 , 19-07-00 1 , 19-29-01047).

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E-mail: matorin@softconnect.ru

, . (« »)

E-mail: keeper121@ya.ru

, . (« »)

E-mail: zhikharev@bsu.edu.ru